

NAG Library Function Document

nag_zgbmv (f16sbc)

1 Purpose

nag_zgbmv (f16sbc) performs matrix-vector multiplication for a complex band matrix.

2 Specification

```
#include <nag.h>
#include <nagf16.h>

void nag_zgbmv (Nag_OrderType order, Nag_TransType trans, Integer m,
               Integer n, Integer kl, Integer ku, Complex alpha, const Complex ab[],
               Integer pdab, const Complex x[], Integer incx, Complex beta,
               Complex y[], Integer incy, NagError *fail)
```

3 Description

nag_zgbmv (f16sbc) performs one of the matrix-vector operations

$$y \leftarrow \alpha Ax + \beta y, \quad y \leftarrow \alpha A^T x + \beta y \quad \text{or} \quad y \leftarrow \alpha A^H x + \beta y$$

where A is an m by n complex band matrix with k_l subdiagonals and k_u superdiagonals, x and y are complex vectors, and α and β are complex scalars.

If $m = 0$ or $n = 0$, no operation is performed.

4 References

Basic Linear Algebra Subprograms Technical (BLAST) Forum (2001) *Basic Linear Algebra Subprograms Technical (BLAST) Forum Standard* University of Tennessee, Knoxville, Tennessee <http://www.netlib.org/blas/blast-forum/blas-report.pdf>

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **trans** – Nag_TransType *Input*

On entry: specifies the operation to be performed.

trans = Nag_NoTrans
 $y \leftarrow \alpha Ax + \beta y.$

trans = Nag_Trans
 $y \leftarrow \alpha A^T x + \beta y.$

trans = Nag_ConjTrans
 $y \leftarrow \alpha A^H x + \beta y.$

Constraint: **trans** = Nag_NoTrans, Nag_Trans or Nag_ConjTrans.

- 3: **m** – Integer *Input*
On entry: m , the number of rows of the matrix A .
Constraint: $\mathbf{m} \geq 0$.
- 4: **n** – Integer *Input*
On entry: n , the number of columns of the matrix A .
Constraint: $\mathbf{n} \geq 0$.
- 5: **kl** – Integer *Input*
On entry: k_l , the number of subdiagonals within the band of A .
Constraint: $\mathbf{kl} \geq 0$.
- 6: **ku** – Integer *Input*
On entry: k_u , the number of superdiagonals within the band of A .
Constraint: $\mathbf{ku} \geq 0$.
- 7: **alpha** – Complex *Input*
On entry: the scalar α .
- 8: **ab**[*dim*] – const Complex *Input*
Note: the dimension, *dim*, of the array **ab** must be at least
 $\max(1, \mathbf{pdab} \times \mathbf{n})$ when **order** = Nag_ColMajor;
 $\max(1, \mathbf{m} \times \mathbf{pdab})$ when **order** = Nag_RowMajor.
On entry: the m by n band matrix A .
This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements A_{ij} , for row $i = 1, \dots, m$ and column $j = \max(1, i - k_l), \dots, \min(n, i + k_u)$, depends on the **order** argument as follows:
if **order** = Nag_ColMajor, A_{ij} is stored as **ab**[($j - 1$) \times **pdab** + **ku** + $i - j$];
if **order** = Nag_RowMajor, A_{ij} is stored as **ab**[($i - 1$) \times **pdab** + **kl** + $j - i$].
- 9: **pdab** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix A in the array **ab**.
Constraint: $\mathbf{pdab} \geq \mathbf{kl} + \mathbf{ku} + 1$.
- 10: **x**[*dim*] – const Complex *Input*
Note: the dimension, *dim*, of the array **x** must be at least
 $\max(1, 1 + (\mathbf{n} - 1)|\mathbf{incx}|)$ when **trans** = Nag_NoTrans;
 $\max(1, 1 + (\mathbf{m} - 1)|\mathbf{incx}|)$ when **trans** = Nag_Trans or Nag_ConjTrans.
On entry: the vector x .
If **trans** = Nag_NoTrans, then x is an n -element vector.
If **incx** > 0, x_i must be stored in **x**[($i - 1$) \times **incx**], for $i = 1, 2, \dots, \mathbf{n}$.
If **incx** < 0, x_i must be stored in **x**[($\mathbf{n} - i$) \times **incx**], for $i = 1, 2, \dots, \mathbf{n}$.
Intermediate elements of **x** are not referenced. If $\mathbf{n} = 0$, **x** is not referenced and may be NULL.

Otherwise, x is an m -element vector.

If $\mathbf{incx} > 0$, x_i must be stored in $\mathbf{x}[(i-1) \times \mathbf{incx}]$, for $i = 1, 2, \dots, \mathbf{m}$.

If $\mathbf{incx} < 0$, x_i must be stored in $\mathbf{x}[(\mathbf{m}-i) \times |\mathbf{incx}|]$, for $i = 1, 2, \dots, \mathbf{m}$.

Intermediate elements of \mathbf{x} are not referenced. If $\mathbf{m} = 0$, \mathbf{x} is not referenced and may be **NULL**.

- 11: **incx** – Integer *Input*
On entry: the increment in the subscripts of \mathbf{x} between successive elements of x .
Constraint: $\mathbf{incx} \neq 0$.
- 12: **beta** – Complex *Input*
On entry: the scalar β .
- 13: **y[*dim*]** – Complex *Input/Output*
Note: the dimension, *dim*, of the array \mathbf{y} must be at least
 $\max(1, 1 + (\mathbf{m} - 1)|\mathbf{incy}|)$ when **trans** = Nag_NoTrans;
 $\max(1, 1 + (\mathbf{n} - 1)|\mathbf{incy}|)$ when **trans** = Nag_Trans or Nag_ConjTrans.
On entry: the vector y . See \mathbf{x} for details of storage.
 If **beta** = 0, \mathbf{y} need not be set.
On exit: the updated vector y .
- 14: **incy** – Integer *Input*
On entry: the increment in the subscripts of \mathbf{y} between successive elements of y .
Constraint: $\mathbf{incy} \neq 0$.
- 15: **fail** – NagError * *Input/Output*
 The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, **incx** = $\langle value \rangle$.

Constraint: **incx** $\neq 0$.

On entry, **incy** = $\langle value \rangle$.

Constraint: **incy** $\neq 0$.

On entry, **kl** = $\langle value \rangle$.

Constraint: **kl** ≥ 0 .

On entry, **ku** = $\langle value \rangle$.

Constraint: **ku** ≥ 0 .

On entry, **m** = $\langle value \rangle$.

Constraint: **m** ≥ 0 .

On entry, **n** = $\langle value \rangle$.

Constraint: **n** ≥ 0 .

NE_INT_3

On entry, **pdab** = $\langle value \rangle$, **kl** = $\langle value \rangle$, **ku** = $\langle value \rangle$.

Constraint: **pdab** \geq **kl** + **ku** + 1.

NE_INTERNAL_ERROR

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

7 Accuracy

The BLAS standard requires accurate implementations which avoid unnecessary over/underflow (see Section 2.7 of Basic Linear Algebra Subprograms Technical (BLAST) Forum (2001)).

8 Parallelism and Performance

nag_zgbmv (f16sbc) is not threaded in any implementation.

9 Further Comments

None.

10 Example

This example computes the matrix-vector product

$$y = \alpha Ax + \beta y$$

where

$$A = \begin{pmatrix} 1.0 + 1.0i & 1.0 + 2.0i & 0.0 + 0.0i & 0.0 + 0.0i \\ 2.0 + 1.0i & 2.0 + 2.0i & 2.0 + 3.0i & 0.0 + 0.0i \\ 3.0 + 1.0i & 3.0 + 2.0i & 3.0 + 3.0i & 3.0 + 4.0i \\ 0.0 + 0.0i & 4.0 + 2.0i & 4.0 + 3.0i & 4.0 + 4.0i \\ 0.0 + 0.0i & 0.0 + 0.0i & 5.0 + 3.0i & 5.0 + 4.0i \\ 0.0 + 0.0i & 0.0 + 0.0i & 0.0 + 0.0i & 6.0 + 4.0i \end{pmatrix},$$

$$x = \begin{pmatrix} 1.0 - 1.0i \\ 2.0 - 2.0i \\ 3.0 - 3.0i \\ 4.0 - 4.0i \end{pmatrix},$$

$$y = \begin{pmatrix} -3.5 + 0.0i \\ -11.5 + 1.0i \\ -27.5 + 3.0i \\ -29.0 + 7.5i \\ -25.5 + 10.0i \\ -14.5 + 10.0i \end{pmatrix},$$

$$\alpha = 1.0 + 0.0i \quad \text{and} \quad \beta = 2.0 + 0.0i.$$

10.1 Program Text

```

/* nag_zgbmv (f16sbc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf16.h>

int main(void)
{
    /* Scalars */
    Complex alpha, beta;
    Integer ab_size, exit_status, i, incx, incy, j, kl, ku;
    Integer m, n, pdab, xlen, ylen;

    /* Arrays */
    Complex *ab = 0, *x = 0, *y = 0;
    char nag_enum_arg[40];

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;
    Nag_TransType trans;

#ifdef NAG_COLUMN_MAJOR
#define AB(I, J) ab[(J-1)*pdab + ku + I - J]
    order = Nag_ColMajor;
#else
#define AB(I, J) ab[(I-1)*pdab + kl + J - I]
    order = Nag_RowMajor;
#endif

    exit_status = 0;
    INIT_FAIL(fail);

    printf("nag_zgbmv (f16sbc) Example Program Results\n\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n] ");
#else
    scanf("%*[\n] ");
#endif

    /* Read the problem dimensions */
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%*[\n] ",
            &m, &n, &kl, &ku);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%*[\n] ",

```

```

        &m, &n, &kl, &ku);
#endif
/* Read the transpose parameter */
#ifdef _WIN32
    scanf_s("%39s%[\n] ", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf("%39s%[\n] ", nag_enum_arg);
#endif
/* nag_enum_name_to_value (x04nac).
 * Converts NAG enum member name to value
 */
trans = (Nag_TransType) nag_enum_name_to_value(nag_enum_arg);
/* Read scalar parameters */
#ifdef _WIN32
    scanf_s(" ( %lf , %lf ) ( %lf , %lf )%[\n] ",
            &alpha.re, &alpha.im, &beta.re, &beta.im);
#else
    scanf(" ( %lf , %lf ) ( %lf , %lf )%[\n] ",
            &alpha.re, &alpha.im, &beta.re, &beta.im);
#endif
/* Read increment parameters */
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%[\n] ", &incx, &incy);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%[\n] ", &incx, &incy);
#endif

    pdab = kl + ku + 1;
#ifdef NAG_COLUMN_MAJOR
    ab_size = pdab * n;
#else
    ab_size = pdab * m;
#endif

    if (trans == Nag_NoTrans) {
        xlen = MAX(1, 1 + (n - 1) * ABS(incx));
        ylen = MAX(1, 1 + (m - 1) * ABS(incy));
    }
    else {
        xlen = MAX(1, 1 + (m - 1) * ABS(incx));
        ylen = MAX(1, 1 + (n - 1) * ABS(incy));
    }

    if (m > 0 && n > 0) {
        /* Allocate memory */
        if (!(ab = NAG_ALLOC(ab_size, Complex)) ||
            !(x = NAG_ALLOC(xlen, Complex)) || !(y = NAG_ALLOC(ylen, Complex)))
        {
            printf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
    }
    else {
        printf("Invalid m or n\n");
        exit_status = 1;
        return exit_status;
    }

    /* Input matrix A and vectors x and y */

    for (i = 1; i <= m; ++i) {
        for (j = MAX(1, i - kl); j <= MIN(n, i + ku); ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &AB(i, j).re, &AB(i, j).im);
#else
            scanf(" ( %lf , %lf )", &AB(i, j).re, &AB(i, j).im);
#endif
    }
#ifdef _WIN32
    scanf_s("%[\n] ");
#else

```

```

        scanf("%*[\n] ");
#endif
    }
    for (i = 1; i <= xlen; ++i)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )%*[\n] ", &x[i - 1].re, &x[i - 1].im);
#else
        scanf(" ( %lf , %lf )%*[\n] ", &x[i - 1].re, &x[i - 1].im);
#endif
    for (i = 1; i <= ylen; ++i)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )%*[\n] ", &y[i - 1].re, &y[i - 1].im);
#else
        scanf(" ( %lf , %lf )%*[\n] ", &y[i - 1].re, &y[i - 1].im);
#endif

    /* nag_zgbmv (f16sbc).
     * Complex valued band matrix-vector multiply.
     */
    nag_zgbmv(order, trans, m, n, kl, ku, alpha, ab, pdab, x,
              incx, beta, y, incy, &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_zgbmv.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }

    /* Print output vector y */
    printf("%s\n", " y");
    for (i = 1; i <= ylen; ++i) {
        printf("(%11f,%11f)\n", y[i - 1].re, y[i - 1].im);
    }

END:
    NAG_FREE(ab);
    NAG_FREE(x);
    NAG_FREE(y);

    return exit_status;
}

```

10.2 Program Data

nag_zgbmv (f16sbc) Example Program Data

```

6 4 2 1           :Values of m, n, kl, ku
Nag_NoTrans      : trans
( 1.0, 0.0) ( 2.0, 0.0)   : alpha, beta
1 1             : incx, incy
( 1.0, 1.0) ( 1.0, 2.0)
( 2.0, 1.0) ( 2.0, 2.0) ( 2.0, 3.0)
( 3.0, 1.0) ( 3.0, 2.0) ( 3.0, 3.0) ( 3.0, 4.0)
                   ( 4.0, 2.0) ( 4.0, 3.0) ( 4.0, 4.0)
                                   ( 5.0, 3.0) ( 5.0, 4.0)
                                           ( 6.0, 4.0) : the end of matrix A

( 1.0,-1.0)
( 2.0,-2.0)
( 3.0,-3.0)
( 4.0,-4.0)           : the end of vector x
(-3.5, 0.0)
(-11.5, 1.0)
(-27.5, 3.0)
(-29.0, 7.5)
(-25.5, 10.0)
(-14.5, 10.0)         : the end of vector y

```

10.3 Program Results

nag_zgbmv (f16sbc) Example Program Results

```
      Y
(   1.000000,   2.000000)
(   3.000000,   4.000000)
(   5.000000,   6.000000)
(   7.000000,   8.000000)
(   9.000000,  10.000000)
(  11.000000,  12.000000)
```
