

## NAG Library Function Document

### nag\_zgels (f08anc)

## 1 Purpose

nag\_zgels (f08anc) solves linear least squares problems of the form

$$\min_x \|b - Ax\|_2 \quad \text{or} \quad \min_x \|b - A^H x\|_2,$$

where  $A$  is an  $m$  by  $n$  complex matrix of full rank, using a  $QR$  or  $LQ$  factorization of  $A$ .

## 2 Specification

```
#include <nag.h>
#include <nagf08.h>
void nag_zgels (Nag_OrderType order, Nag_TransType trans, Integer m,
                Integer n, Integer nrhs, Complex a[], Integer pda, Complex b[],
                Integer pdb, NagError *fail)
```

## 3 Description

The following options are provided:

1. If **trans** = Nag\_NoTrans and  $m \geq n$ : find the least squares solution of an overdetermined system, i.e., solve the least squares problem

$$\min_x \|b - Ax\|_2.$$

2. If **trans** = Nag\_NoTrans and  $m < n$ : find the minimum norm solution of an underdetermined system  $Ax = b$ .
3. If **trans** = Nag\_ConjTrans and  $m \geq n$ : find the minimum norm solution of an undetermined system  $A^H x = b$ .
4. If **trans** = Nag\_ConjTrans and  $m < n$ : find the least squares solution of an overdetermined system, i.e., solve the least squares problem

$$\min_x \|b - A^H x\|_2.$$

Several right-hand side vectors  $b$  and solution vectors  $x$  can be handled in a single call; they are stored as the columns of the  $m$  by  $r$  right-hand side matrix  $B$  and the  $n$  by  $r$  solution matrix  $X$ .

## 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

## 5 Arguments

- 1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by

**order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **trans** – Nag\_TransType *Input*

*On entry:* if **trans** = Nag\_NoTrans, the linear system involves  $A$ .

If **trans** = Nag\_ConjTrans, the linear system involves  $A^H$ .

*Constraint:* **trans** = Nag\_NoTrans or Nag\_ConjTrans.

3: **m** – Integer *Input*

*On entry:*  $m$ , the number of rows of the matrix  $A$ .

*Constraint:* **m**  $\geq 0$ .

4: **n** – Integer *Input*

*On entry:*  $n$ , the number of columns of the matrix  $A$ .

*Constraint:* **n**  $\geq 0$ .

5: **nrhs** – Integer *Input*

*On entry:*  $r$ , the number of right-hand sides, i.e., the number of columns of the matrices  $B$  and  $X$ .

*Constraint:* **nrhs**  $\geq 0$ .

6: **a**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **a** must be at least

$\max(1, \mathbf{pda} \times \mathbf{n})$  when **order** = Nag\_ColMajor;  
 $\max(1, \mathbf{m} \times \mathbf{pda})$  when **order** = Nag\_RowMajor.

The  $(i, j)$ th element of the matrix  $A$  is stored in

$\mathbf{a}[(j - 1) \times \mathbf{pda} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{a}[(i - 1) \times \mathbf{pda} + j - 1]$  when **order** = Nag\_RowMajor.

*On entry:* the  $m$  by  $n$  matrix  $A$ .

*On exit:* if  $\mathbf{m} \geq \mathbf{n}$ , **a** is overwritten by details of its  $QR$  factorization, as returned by nag\_zgeqr (f08asc).

If  $\mathbf{m} < \mathbf{n}$ , **a** is overwritten by details of its  $LQ$  factorization, as returned by nag\_zgelqf (f08avc).

7: **pda** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **a**.

*Constraints:*

if **order** = Nag\_ColMajor, **pda**  $\geq \max(1, \mathbf{m})$ ;  
if **order** = Nag\_RowMajor, **pda**  $\geq \max(1, \mathbf{n})$ .

8: **b**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **b** must be at least

$\max(1, \mathbf{pdb} \times \mathbf{nrhs})$  when **order** = Nag\_ColMajor;  
 $\max(1, \max(1, \mathbf{m}, \mathbf{n}) \times \mathbf{pdb})$  when **order** = Nag\_RowMajor.

The  $(i, j)$ th element of the matrix  $B$  is stored in

$$\begin{aligned} \mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1] &\text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ \mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1] &\text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On entry:* the matrix  $B$  of right-hand side vectors, stored in rows or columns;  $\mathbf{b}$  is  $m$  by  $r$  if  $\mathbf{trans} = \text{Nag\_NoTrans}$ , or  $n$  by  $r$  if  $\mathbf{trans} = \text{Nag\_ConjTrans}$ .

*On exit:*  $\mathbf{b}$  is overwritten by the solution vectors,  $x$ , stored in rows or columns:

if  $\mathbf{trans} = \text{Nag\_NoTrans}$  and  $m \geq n$ , or  $\mathbf{trans} = \text{Nag\_ConjTrans}$  and  $m < n$ , elements 1 to  $\min(m, n)$  in each column of  $\mathbf{b}$  contain the least squares solution vectors; the residual sum of squares for the solution is given by the sum of squares of the modulus of elements  $(\min(m, n) + 1)$  to  $\max(m, n)$  in that column;

otherwise, elements 1 to  $\max(m, n)$  in each column of  $\mathbf{b}$  contain the minimum norm solution vectors.

9: **pdb** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.

*Constraints:*

if  $\mathbf{order} = \text{Nag\_ColMajor}$ ,  $\mathbf{pdb} \geq \max(1, \mathbf{m}, \mathbf{n})$ ;  
 if  $\mathbf{order} = \text{Nag\_RowMajor}$ ,  $\mathbf{pdb} \geq \max(1, \mathbf{nrhs})$ .

10: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle \text{value} \rangle$  had an illegal value.

### NE\_FULL\_RANK

Diagonal element  $\langle \text{value} \rangle$  of the triangular factor of  $A$  is zero, so that  $A$  does not have full rank; the least squares solution could not be computed.

### NE\_INT

On entry,  $\mathbf{m} = \langle \text{value} \rangle$ .  
 Constraint:  $\mathbf{m} \geq 0$ .

On entry,  $\mathbf{n} = \langle \text{value} \rangle$ .  
 Constraint:  $\mathbf{n} \geq 0$ .

On entry,  $\mathbf{nrhs} = \langle \text{value} \rangle$ .  
 Constraint:  $\mathbf{nrhs} \geq 0$ .

On entry,  $\mathbf{pda} = \langle \text{value} \rangle$ .  
 Constraint:  $\mathbf{pda} > 0$ .

On entry,  $\mathbf{pdb} = \langle \text{value} \rangle$ .  
 Constraint:  $\mathbf{pdb} > 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$  and **m** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, m)$ .

On entry, **pda** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, n)$ .

On entry, **pdb** =  $\langle value \rangle$  and **nrhs** =  $\langle value \rangle$ .

Constraint: **pdb**  $\geq \max(1, nrhs)$ .

**NE\_INT\_3**

On entry, **pdb** =  $\langle value \rangle$ , **m** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .

Constraint: **pdb**  $\geq \max(1, m, n)$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

## 7 Accuracy

See Section 4.5 of Anderson *et al.* (1999) for details of error bounds.

## 8 Parallelism and Performance

`nag_zgels` (f08anc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

`nag_zgels` (f08anc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The total number of floating-point operations required to factorize  $A$  is approximately  $\frac{8}{3}n^2(3m - n)$  if  $m \geq n$  and  $\frac{8}{3}m^2(3n - m)$  otherwise. Following the factorization the solution for a single vector  $x$  requires  $O(\min(m^2, n^2))$  operations.

The real analogue of this function is `nag_dgels` (f08aac).

## 10 Example

This example solves the linear least squares problem

$$\min_x \|b - Ax\|_2,$$

where

$$A = \begin{pmatrix} 0.96 - 0.81i & -0.03 + 0.96i & -0.91 + 2.06i & -0.05 + 0.41i \\ -0.98 + 1.98i & -1.20 + 0.19i & -0.66 + 0.42i & -0.81 + 0.56i \\ 0.62 - 0.46i & 1.01 + 0.02i & 0.63 - 0.17i & -1.11 + 0.60i \\ -0.37 + 0.38i & 0.19 - 0.54i & -0.98 - 0.36i & 0.22 - 0.20i \\ 0.83 + 0.51i & 0.20 + 0.01i & -0.17 - 0.46i & 1.47 + 1.59i \\ 1.08 - 0.28i & 0.20 - 0.12i & -0.07 + 1.23i & 0.26 + 0.26i \end{pmatrix}$$

and

$$b = \begin{pmatrix} -2.09 + 1.93i \\ 3.34 - 3.53i \\ -4.94 - 2.04i \\ 0.17 + 4.23i \\ -5.19 + 3.63i \\ 0.98 + 2.53i \end{pmatrix}.$$

The square root of the residual sum of squares is also output.

## 10.1 Program Text

```
/* nag_zgels (f08anc) Example Program.
*
* NAGPRODCODE Version.
*
* Copyright 2016 Numerical Algorithms Group.
*
* Mark 26, 2016.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stdl�.h>
#include <nagf08.h>
#include <nagf16.h>

int main(void)
{
    /* Scalars */
    double rnorm;
    Integer exit_status = 0, i, j, m, n, nrhs, pda, pdb;
    /* Arrays */
    Complex *a = 0, *b = 0;
    /* Nag Types */
    Nag_OrderType order;
    NagError fail;

#ifdef NAG_COLUMN_MAJOR
#define A(I, J) a[(J - 1) * pda + I - 1]
#define B(I, J) b[(J - 1) * pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J) a[(I - 1) * pda + J - 1]
#define B(I, J) b[(I - 1) * pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_zgels (f08anc) Example Program Results\n\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[^\n]");
#else
    scanf("%*[^\n]");
#endif
#ifdef _WIN32

```

```

    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%*[^\n]", &m, &n, &nrhs);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "%*[^\n]", &m, &n, &nrhs);
#endif

/* Allocate memory */
if (!(a = NAG_ALLOC(m * n, Complex)) || !(b = NAG_ALLOC(m * nrhs, Complex)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

#ifndef NAG_COLUMN_MAJOR
    pda = m;
    pdb = m;
#else
    pda = n;
    pdb = nrhs;
#endif

/* Read A and B from data file */
for (i = 1; i <= m; ++i)
    for (j = 1; j <= n; ++j)
#ifdef _WIN32
    scanf_s(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#else
    scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*[^\n]");
#else
    scanf("%*[^\n]");
#endif

    for (i = 1; i <= m; ++i)
        for (j = 1; j <= nrhs; ++j)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
        scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
        scanf_s("%*[^\n]");
#else
        scanf("%*[^\n]");
#endif

/* nag_zgels (f08anc).
 * Solve the least squares problem min( norm2(b - Ax) ) for x.
 */
nag_zgels(order, Nag_NoTrans, m, n, nrhs, a, pda, b, pdb, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zgels (f08anc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print solution */
printf("Least squares solution\n");
for (i = 1; i <= n; ++i) {
    for (j = 1; j <= nrhs; ++j)
        printf("(%.4f, %.4f)%s", B(i, j).re, B(i, j).im,
               j % 4 == 0 ? "\n" : " ");
    printf("\n");
}

/* nag_zge_norm (f16uac).
 * Compute and print estimate of the square root of the residual
 * sum of squares.
 */

```

```

nag_zge_norm(order, Nag_FrobeniusNorm, m - n, 1, &B(n + 1, 1), pdb, &rnorm,
             &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_norm (f16uac).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

printf("\nSquare root of the residual sum of squares\n");
printf("%11.2e\n", rnorm);

END:
NAG_FREE(a);
NAG_FREE(b);

return exit_status;
}

#undef A
#undef B

```

## 10.2 Program Data

nag\_zgels (f08anc) Example Program Data

```

6           4           1           :Values of m, n and nrhs
( 0.96,-0.81) (-0.03, 0.96) (-0.91, 2.06) (-0.05, 0.41)
(-0.98, 1.98) (-1.20, 0.19) (-0.66, 0.42) (-0.81, 0.56)
( 0.62,-0.46) ( 1.01, 0.02) ( 0.63,-0.17) (-1.11, 0.60)
(-0.37, 0.38) ( 0.19,-0.54) (-0.98,-0.36) ( 0.22,-0.20)
( 0.83, 0.51) ( 0.20, 0.01) (-0.17,-0.46) ( 1.47, 1.59)
( 1.08,-0.28) ( 0.20,-0.12) (-0.07, 1.23) ( 0.26, 0.26) :End of matrix A

(-2.09, 1.93)
( 3.34,-3.53)
(-4.94,-2.04)
( 0.17, 4.23)
(-5.19, 3.63)
( 0.98, 2.53)           :End of vector b

```

## 10.3 Program Results

nag\_zgels (f08anc) Example Program Results

```

Least squares solution
(-0.5044, -1.2179)
(-2.4281,  2.8574)
( 1.4872, -2.1955)
( 0.4537,  2.6904)

```

```

Square root of the residual sum of squares
 6.88e-02

```

---